

Designing of integrated cyber-physical systems - opis przedmiotu

Informacje ogólne

Nazwa przedmiotu	Designing of integrated cyber-physical systems
Kod przedmiotu	11.3-WE-INF-DofIC-PS-Er
Wydział	Wydział Informatyki, Elektrotechniki i Automatyki
Kierunek	Informatyka
Profil	ogółnoakademicki
Rodzaj studiów	Program Erasmus drugiego stopnia
Semestr rozpoczęcia	semestr zimowy 2020/2021

Informacje o przedmiocie

Semestr	2
Liczba punktów ECTS do zdobycia	5
Typ przedmiotu	obowiązkowy
Język nauczania	angielski
Syllabus opracował	• dr hab. inż. Remigiusz Wiśniewski, prof. UZ

Formy zajęć

Forma zajęć	Liczba godzin w semestrze (stacjonarne)	Liczba godzin w tygodniu (stacjonarne)	Liczba godzin w semestrze (niestacjonarne)	Liczba godzin w tygodniu (niestacjonarne)	Forma zaliczenia
Wykład	15	1	-	-	Zaliczenie na ocenę
Laboratorium	30	2	-	-	Zaliczenie na ocenę
Projekt	15	1	-	-	Zaliczenie na ocenę

Cel przedmiotu

- Familiarize students with the designing methods of a control part of an integrated cyber-physical systems.
- Familiarize students with the basic knowledge about specification, analysis, and implementation of a control part of an integrated cyber-physical systems.

Wymagania wstępne

Zakres tematyczny

Introduction: cyber-physical system (CPS), concurrent control system, smart system, Internet of Things (IoT), integrated and distributed systems.

General designing flow of a control part of an integrated cyber-physical system: specification, analysis (validation, verification), decomposition and synchronization, designing of the decomposed system, functional verification, implementation.

Graphical specification methods of a control part of an integrated CPS: Petri nets, interpreted Petri nets, UML diagrams.

Analysis of a control part of an integrated CPS: validation, formal verification, concurrency and sequentiality analysis with the application of linear algebra (invariants), graph and hypergraph theories. Liveness, boundedness and safeness. Computational complexity of analysis algorithms.

Decomposition and synchronization of the system: decomposition into sequential automata (state machine components), decomposition methods (linear algebra, graph theory, hypergraph theory), time domains, synchronization of decomposed modules.

Designing of the decomposed system: finite state machines (FSMs), microprogrammed controllers, description in the hardware languages (Verilog, VHDL).

Implementation of the system: logic synthesis, physical implementation of the system in the FPGA device.

Static partial reconfiguration of already implemented system.

Dynamic partial reconfiguration of already implemented system.

Metody kształcenia

Lecture, laboratory exercises, project.

Efekty uczenia się i metody weryfikacji osiągania efektów uczenia się

Opis efektu	Symbole efektów	Metody weryfikacji	Forma zajęć
Has a basic knowledge on designing of a control part of an integrated cyber-physical systems with the application of graphical methods (Petri nets)		<ul style="list-style-type: none">• aktywność w trakcie zajęć• dyskusja• kolokwium	<ul style="list-style-type: none">• Wykład• Laboratorium

Opis efektu	Symboli efektów	Metody weryfikacji	Forma zajęć
Has a knowledge about various analysis and decomposition methods of a control part of an integrated cyber-physical system (in regards of computational complexity of algorithms)		<ul style="list-style-type: none"> aktywność w trakcie zajęć dyskusja kolokwium 	<ul style="list-style-type: none"> Wykład
Is able to design a control part of an integrated cyber-physical system with the application of graphical specification methods (e.g. Petri nets).		<ul style="list-style-type: none"> aktywność w trakcie zajęć bieżąca kontrola na zajęciach projekt 	<ul style="list-style-type: none"> Laboratorium Projekt

Warunki zaliczenia

Lecture – the passing condition is to obtain a positive mark from the final test (or other tasks given by the teacher).

Laboratory – the passing condition is to obtain positive marks from all laboratory exercises to be planned during the semester (or other tasks given by the teacher).

Project – the passing condition is to obtain a positive mark from all projects conducted during the semester (or other task given by the teacher).

Final mark components: lecture 30% + laboratory 40% + project 30%.

Literatura podstawowa

1. E. A. Lee, S. A. Seshia, *Introduction to Embedded Systems: A Cyber-Physical Systems Approach*, Cambridge, MA, USA:MIT Press, 2017, https://ptolemy.berkeley.edu/books/leeseshia/releases/LeeSeshia_DigitalV2_2.pdf
2. R. Alur, *Principles of Cyber-Physical Systems*, MIT Press, 2015.
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5. R. Wiśniewski, *Prototyping of Concurrent Control Systems Implemented in FPGA Devices*, Cham, Switzerland:Springer, 2017, <https://link.springer.com/content/pdf/10.1007/978-3-319-45811-3.pdf>

Literatura uzupełniająca

1. Best, R. Devillers, M. Koutny, *Petri Net Algebra*, Berlin, Germany:Springer-Verlag, 2013.
2. I. Grobelna, R. Wiśniewski, M. Grobelny, M. Wiśniewska, "Design and verification of real-life processes with application of Petri nets", *IEEE Trans. Syst. Man Cybern. Syst.*, vol. 47, no. 11, pp. 2856-2869, Nov. 2017.
3. L. Gomes, A. Costa, J. P. Barros, P. Lima, "From Petri net models to VHDL implementation of digital controllers", *Proc. IEEE 33rd Annu. Conf.*, pp. 94-99, Nov. 2007.
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7. R. Wiśniewski, "Dynamic partial reconfiguration of concurrent control systems specified by Petri nets and implemented in Xilinx FPGA devices", *IEEE Access*, vol. 6, pp. 32376-32391, 2018, DOI: <http://dx.doi.org/10.1109/ACCESS.2018.2836858>.
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11. R. Wiśniewski, G. Bazydło, P. Szcześniak, I. Grobelna, M. Wojnakowski, „Design and Verification of Cyber-Physical Systems Specified by Petri Nets - A Case Study of a Direct Matrix Converter”, *Mathematics*, vol. 7, pp. 1-24, 2019, DOI: <https://doi.org/10.3390/math7090812>.
12. V. Hahanov et al., "Cyber social computing" in Social Business and Industrial Applications, Cham, Switzerland:Springer, pp. 489-515, 2019.
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Uwagi

Zmodyfikowane przez dr hab. inż. Remigiusz Wiśniewski, prof. UZ (ostatnia modyfikacja: 23-04-2020 23:59)

Wygenerowano automatycznie z systemu SylabUZ